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New storage: design principles

- > Installed February 2020
- > Rather than using a single file system and hardware technology for all volumes, we decided this time to go for a mixed setup
 - Traditional file systems exported over NFS may be a better choice to deal with the metadata operations overload and inefficient volume use caused by packages that install tons of small files (e.g., Python, R and MATLAB)
 - Parallel file systems offer a much better price/performance and price/volume ratio
 - Limited use of SSD
 - SSDs have poor lifespan when used in the wrong way (i.e, high write/erase load and lots of small write operations)
 - Data center quality long-life SSDs are up to 20 times more expensive per TB than hard disks
- > Tried to make our storage even more independent from the cluster to make it easier to keep the storage available during system maintenance periods
 - $_{\rm o}$ So you'd still be able to run on other VSC-clusters







New storage: Parallel scratch file system

➤ Scratch

• Parallel file system: switched to BeeGFS rather than GPFS / SpectrumScale

- Storage:
 - Metadata on redundant SSDs (mirroring)
 - Data on 7 hard disk pools of 14 drives
- Highest capacity of all our storage systems: 0.6 PB and room to grow
- Highest bandwidth: up to 7 GB/s combined over all users and nodes
 - But this requires the right access profile in software
- You can request a very high block quota but the number of files that you can store will be limited as HPC storage is designed to work with large files
- Technologies such as HDF5 and netCDF are designed to store data in a portable and structured way that is more efficient than using tons of small files in a directory structure...

Quota							
 Shown at Or run my Current de 	login /quota efaults:						
		block quota	file quota				
	/home	3 GB	20,000				
	/data	25 GB	100,000				
	/scratch	50 GB	100,000				
 For scratch the file quotum is actually not the number of files that you see, but the number of files occupied on the storage system. Large files can be split in multiple files (called chunk files in BeeGFS), but this is hidden from the user (and in fact increases performance). 							
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Cluster overview					
Leibniz (2017)	Vaughan (2020-2021)				
• 152 regular compute nodes	• 152 compute nodes				
○144*128GB, 8*256GB	0 256GB				
o 2 2.4GHz 14-core Broadwell CPUs (E5-2680v4)	o 2 2.35GHz 32-core AMD Rome CPUs (7452)				
$_{\odot}\text{No}$ swap, small local tmp for OS	$\circ\text{No}$ swap, small local tmp for OS				
• 24 256 GB nodes from Hopper still attached					
• 2 GPU compute nodes (dual Tesla P100)					
• 1 NEC SX Aurora node					
 2 login nodes (identical CPU to the compute nodes) 	• 2 login nodes (2 16-core AMD EPYC 7282 CPUs each)				
• 1 visualisation node (hardware accelerated OpenGL)					
The storage is a joint setup for Leibniz and Vaughan with more than 650TB capacity spread over a number of volumes					

Why AMD?

> Similar theoretical peak performance with AMD (Rome) and Intel (Cascade Lake)

- AMD reaches this by using more cores but sticking with AVX2 vector instructions
- o Intel reaches this by using less cores but a vector instruction set with longer vectors (AVX512)
- Added bonus is some initial support for operations that are popular in neural networks
 Performance per core for scalar operations similar on both
- > AMD offers significantly more memory bandwidth per socket
 - AMD: 8 64-bit channels per socket, 3200 MHz data rate
 - Intel: 6 64-bit channels per socket, 2666 MHz data rate
 - However, AMD has worse memory latency but compensates this partially with larger caches
- > Looking at benchmarks, we concluded that for the majority of our users AMD was the better choice
 - Codes are often memory bandwidth constrained
 - Several codes don't offer much vectorisation so more net performance on AMD
 - o Benchmark mix we looked at: AMD node can do 60-80% more work than Intel node
- > Diversity in the VSC: Intel Cascade Lake available elsewhere

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The processor							
	Leibniz	Vaughan					
CPU	Intel Broadwell E5-2680v4	AMD Rome 7452					
Base clock speed	2.4 GHz	2.35 GHz	-2%				
Cores/node	28	64	+130%				
Vector instructions	AVX2+FMA	AVX2+FMA					
DP flops/core/cycle	16 (e.g., FMA instruction)	16 (e.g., FMA instruction)	+0%				
Memory speed	8*64b*2400MHz DDR4	16*64b*3200MHz DDR4	+166%				
Theoretical peak/node	851/1075/1254 Gflops (base/2.4GHz/turbo)	2400 (base)	+182% - +152%				
DGEMM Gflops 50k x 50k	995 Gflops	Roughly 2 TFlops					
 Note that core speed didn't increase anymore; the number of cores did Expect similar to slightly higher IPC on Vaughan 							

> No major changes to the instruction set this time

> But check our documentation if you are an Intel compiler user!





Need to know more?	
 All this hardware stuff sounds like Chinese to you? Follow the "Supercomputers for Starters" of our introduction courses See recorded session on the CalcUA web site, in particular the "Processors in supercomput part 	ters"
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Building your environment: Software stack modules and application modules

- Software stack modules:
 - calcua/2020a: Enables only the 2020a compiler toolchain modules (one version of the Intel compiler and a compatible version of the GNU compilers), software built with those compilers, software built with the system compilers and some software installed from binaries
 - Older software stacks have not been reinstalled as the 2019 Intel compilers were transitional and as the 2018 compilers are not supported on CentOS 8.
 - calcua/supported: Enables all currently supported application modules: up to 4 toolchain versions and the system toolchain modules
 - Easy shortcut, but support for this software stack module may disappear
 - So it is a good practice to always load the appropriate software stack module first before loading any other module!
 - o Moving away from leibniz/... and vaughan/... to calcua/... which works on all CalcUA clusters.

Building your environment: Software stack modules and application modules > 3 types of application modules o Built for a specific software stack, e.g., 2020a, and compiler (intel-2020a, GCCcore-9.3.0, ...) Modules in a subdirectory that contains the software stack version in the name Compiler is part of the module name Try to support a toolchain for 2 years • Applications installed in the system toolchain (compiled with the system compilers) Modules in subdirectory system For tools that don't take much compute time or are needed to bootstrap the regular compiler toolchains o Generic binaries for 64-bit Intel-compatible systems Typically applications installed from binary packages Modules in subdirectory software-x86_64 Try to avoid this as this software is usually far from optimally efficient on the system SUPERCOMPUTER













Slurm workload manager > Torque and Moab has served us well for over 10 years > However, in 2016 Adaptive Computing was acquired by another company and since then development has nearly halted and support is bad > New resource manager and scheduling software: Slurm • At the moment the dominant scheduler in academic computing centers Developed at Lawrence Livermore National Lab as an extensible resource manager (2002) o Sophisticated scheduling features have been added since 2008 o Development now largely coordinated by a spin-off, SchedMD LLC. > Single package for resource management and scheduling ensures more logical command line options. > There is a plugin that provides some compatibility with Torque, but since it is buggy and limited we prefer to fully switch to Slurm job scripts We've been preparing for this for over 2 years by stressing those features in Torque that resemble those of Slurm during the introductory courses VLAAMS SUPERCOMPUTER







Important concepts

- > Node: As before, the hardware that runs a single operating system image
- > Core: Physical core in a system
- > CPU: A virtual core in a system (hardware thread). On CalcUA clusters: core = CPU.
- > Partition: A job queue with limits and access control
- > Job: A resource allocation request
- > Job step: A set of (possibly parallel) tasks within a job
 - $_{\circ}$ The job script itself is a special step called the batch job step
 - A MPI application typically runs in its own job step
- > Task: Executes in a job step and corresponds to a Linux process:
 - A shared memory program is a single task
 - MPI application: Each rank (=MPI process) is a task
 - Pure MPI: Each task uses a single CPU (also single core for us)
 - Hybrid MPI/OpenMP: Each task uses multiple CPUs
 - A single task can not use more CPUs than available in a single node







The job environment Some important differences

Torque/MOAB	Slurm
Job starts in a clean login environment (unless –V is used)	 Job copies the environment from which the job was submitted > Risk: Not everything in the environment makes sense on a compute node
 Job starts in the home directory cd \$PBS_0_WORKDIR to move to the directory from which the job was submitted 	 Job starts in the directory from which the job was submitted > Remove cd \$PBS_0_WORKDIR or you'll end up in your home directory!
No process starter for MPI programs included > Made starting of hybrid MPI/OpenMP jobs cumbersome	 Comes with a very versatile process starter, srun If you use I_MPI-environment variables in your job script, you'll have to change some!









Slurm resource requests Requesting memory

- > This is different from Torque
 - $_{\rm o}$ Torque version 2 syntax: physical (RAM) and virtual memory per task
 - o Slurm
 - Specified per CPU and not per task
 - Just a single parameter corresponding to RAM
- > Specifying the amount: Only integers allowed!
 - $_{\circ}$ 10k or 10K is 10 kilobyte
 - 10m or 10M is 10 megabyte (default)
 - 10g or 10G is 10 gigabyte but 3.5g is invalid!
- > Requesting memory:
 - Long option: --mem-per-cpu=3072m or --mem-per-cpu 3072m will allocate 3072 MB = 3 GB per task.
 - $_{\circ}\,$ There is no short option.
- > 240 GB available on Vaughan, so 3840m per core.





Slurm resource requests Faster communication

- > The communication network of both Vaughan and Leibniz have a tree structure
 - Nodes are grouped on a number of edge switches (24 per switch on Leibniz, up to 44 on Vaughan)
 - These switches are connected with one another through a second level of switches, the top switches
 - Hence traffic between two nodes either passes through just a single switch or through three switches (edge – top – edge)
- > Some programs are extremely latency-sensitive and run much better if they only get nodes connected to a single switch
 - Example: GROMACS
- > Requesting nodes on a single switch: --switches=1
 - But this will increase your waiting time...



Slurm resource requests Partitions

- Torque automatically assigned a job to the optimal queue on our systems Slurm does not automatically assign a job to the optimal partition (Slurm equivalent of Torque queue)
- > The default partition is OK for most jobs on our cluster
- > Partitions: scontrol show partition or in the output of sinfo
 - vaughan : Default partition, for regular jobs up to 3 days, single user per node
 - short : Partition for shorter jobs, up to 6 hours. Priority boost and higher node limit.
 - debug : Partition for debugging scripts. Dedicated resources, but not more than 2 nodes, and just a single job in the queue
- \succ Specifying the partition: No need to specify if the default partition is OK
 - Long option: --partition=short or --partition short submits the job to partition short
 Short option: -p short or -pshort submits the job to partition short
- Check the documentation page for the individual cluster for the available partitions (e.g., <u>for</u> <u>vaughan</u>)













Slurm job environment	
 A Slurm job inherits the environment from the shell from which the allocation was m This includes loaded modules, which can be a problem as those modules were not I the context of the compute node Hence it is best to clean and rebuild the environment: moduleforce purge module load calcua/2020a module load MyApplication We are looking for a more elegant way and announce if we found one. 	iade oaded in
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- > Slurm also defines a lot of variables when a job is started. Some are not always present.
 - **\$SLURM_SUBMIT_DIR** : The directory from which sbatch was invoked
 - o \$SLURM_JOB_ID : The Slurm jobID
 - $_{\circ}$ <code>\$SLURM_JOB_NAME</code> : The name of the job
 - \$SLURM_NTASKS : The number of tasks requested/allocated for the job if this was specified in the request, otherwise it depends on how the request was made
 - \$SLURM_CPUS_PER_TASK : Number of CPUs per task if this was specified in the request
 - \$SLURM_JOB_NODELIST : List of nodes allocated to the job
- $_{\circ}$ Additional variables for array jobs, see the example later in the session
- > Full list: <u>sbatch manual page</u>, section "OUTPUT ENVIRONMENT VARIABLES".
 - Not all variables are always defined!
- > And there are of course the VSC_* variables and the various EB* variables when modules are loaded.

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Slurm commands Submitting a batch script: sbatch

- > Basically the equivalent of qsub in Torque
- > sbatch <sbatch arguments> MyJobScript <arguments of job script>
 - $_{\circ}$ Exits immediately when the job is submitted, so it does not wait for the job to start or end
 - $_{\rm o}$ Can also read the job script from stdin instead
- > What it does:
 - Makes a copy of the environment as seen by the command (exported environment variables)
 - o Submits the job script to the selected partition
- > What Slurm then does after sbatch returns:
 - o Creates the allocation when resources become available
 - Creates the batch job step in which the batch script runs, using the environment saved by sbatch and passing the command line arguments of the job script to the job script
- > The sbatch command returns the job id but as part of a sentence
 - Return just the jobid for a succesfully submitted script: Use --parsable (may work differently in the future)

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Slurm commands Creating only an allocation: salloc

> Dangerous command but very useful for interactive work

- o But you have to realise very well what you're doing and understand environments
- > What salloc does:
 - Request the resources (specified on the command line or through environment variables) to Slurm and wait until they are allocated
 - o Then starts a shell on the node where you executed salloc (usually the login node)
 - And this is the confusing part as most likely the shell prompt will look identical to the one you usually get so you won't realise you're still working in the allocation
 - $_{\rm o}$ Frees the resources when you exit the shell or your requested time expires
- > From the shell you can then start job steps on the allocated resources using srun.



















Slurm commands Getting an overview of the cluster: sinfo > Show information about partitions (=queues) and nodes in the cluster > Default behaviour: Per partition \$ sinfo PARTITION AVAIL TIMELIMIT NODES STATE NODELIST vaughan* up 3-00:00:00 146 alloc r1c01cn[1-4],r1c02cn[1-4], ... vaughan* up 3-00:00:00 6 idle r1c03cn4,r1c04cn3,r2c02cn2, ... 6:00:00 146 alloc r1c01cn[1-4],r1c02cn[1-4], ... short up 6:00:00 6 idle r1c03cn4,r1c04cn3,r2c02cn2, ... short up 146 alloc r1c01cn[1-4],r1c02cn[1-4], ... debug up 1:00:00 debug 1:00:00 6 idle r1c03cn4,r1c04cn3,r2c02cn2, ... up • Shows that jobs have a wall time limit of 3 days in partition vaughan $_{\circ}$ 146 nodes are running jobs and 6 are idle at the moment • Note that this does not mean that your job will start, as you may already be using the maximum allowed for a single user. SUPERCOMPUTER

Node-orie	nted ov	erview:								
\$ sinfo -N	N -1									
NODELIST	NODES	PARTITION	STATE CF	PUS	S:C:T	MEMORY	TMP_DISK	WEIGHT	AVAIL_FE	REASON
r1c01cn1	1	short	allocated 64	4	2:32:1	245760	0	1	r1,r1c01	none
r1c01cn1	1	vaughan*	allocated 64	4	2:32:1	245760	0	1	r1,r1c01	none
r1c01cn1	1	debug	allocated 64	4	2:32:1	245760	0	1	r1,r1c01	none
r1c01cn2	1	short	allocated 64	4	2:32:1	245760	0	1	r1,r1c01	none
r1c01cn2	1	vaughan*	allocated 64	4	2:32:1	245760	0	1	r1,r1c01	none
r1c01cn2	1	debug	allocated 64	4	2:32:1	245760	0	1	r1,r1c01	none
Shows to	which p	partitions a	node belongs							
o Shows t	he mem	ory that ca	n be allocated	in KB	3					
 Shows the socket, 1 	he struc HW thr	ture of the read per phy	node in the S: /sical core (CP	:C:T co PU in S	olumn: 2 Slurm)	2:32:1 sta	ands for 2	socket	s, 32 core	s per

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Slurm commands Advanced job control: scontrol

- The scontrol command is mostly for administrators, but some of its features are useful for regular users also, and in particular the show subcommand to show all kinds of information about your job.
- Show information about a running job:
 \$ scontrol -d show job 12345
 will show a lot of information about the job with jobid 12345
- To get a list of node names in a job script that is not in abbreviated notation but can be used to generate node lists for programs that require this (such as NAMD in some situation):
 \$ scontrol show hostnames

in the context of a job will show the allocated host names, one per line:

r5c09cn3\$ echo \$SLURM_NODELIST r5c09cn[3-4] r5c09cn3\$ scontrol show hostnames r5c09cn3 r5c09cn4















#!/bin/bash	generic-hybrid.slurm
#SBATCHjob-name hybrid_hello	
<pre>#SBATCHntasks=8cpus-per-task=16 #SBATCHmem-per-cpu=1g #SBATCHtime=00:05:00 moduleforce purge</pre>	← 8 MPI processes with 16 threads each, i.e., 2 nodes with 64 processes each on Vaughan
module load calcua/2020a	\leftarrow load the software stack module
module load vsc-tutorial	← load vsc-tutorial, which also loads the Intel toolchain (for the MPI libraries)
<pre>export OMP_NUM_THREADS=\$SLURM_CPUS_PER_TASK</pre>	\leftarrow Set the number of OpenMP threads
export OMP_PROC_BIND=true	← Will cause the threads to be nicely spread over the cores and stay on the core
srun mpi_omp_hello	← run the MPI program (mpi_omp_hello) srun does all the magic, but mpirun would work too with Intel MPI









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Atools Example: Parameter exploration

- > Assume we have a range of parameter combinations we want to test in a .csv file (easy to make with Excel)
- > Help offered by atools:
 - *How many jobs should we submit?* atools has a command that will return the index range based on the .csv file
 - *How to get parameters from the .csv file to the program?* atools offers a command to parse a line from the .csv file and store the values in environment variables.
 - *How to check if the code produced results for a particular parameter combination*? atools provides a logging facility and commands to investigate the logs.



Atools Remarks

- > Atools has a nice logging feature that helps to see which work items failed or did not complete and to restart those.
- > Advanced feature of atools: Limited support for some Map-Reduce scenarios:
 - Preparation phase that splits up the data in manageable chunks needs to be done on the login nodes or on separate nodes
 - Parallel processing of these chunks
 - $_{\rm o}$ Atools does offer features to aggregate the results
- > Atools is really just a bunch of Python scripts and it does rely on the scheduler to start all work items
 - o It supports all types of jobs the scheduler support
 - But it is less efficient than worker for very small jobs as worker does all the job management for the work items (including starting them)
 - $_{
 m o}$ A version of worker that can be ported to Slurm is under development

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Further reading on array jobs and parameter exploration

- > atools manual on readthedocs
- > Presentation and training materials used in the course @ KULeuven on Worker and atools. This material is based on Torque but still useful.
- Examples in /apps/antwerpen/examples/atools/Slurm, or point your browser to github.com/hpcuantwerpen/cluster-examples to have all documentation nicely formatted.

















Dependent Example	obs			
> After start of the f	rst job – squeue			
JOBID	ARTITION NAME USER	ST TIME	NODES NODELIST(REASON)	
24869	vaughan job_mult vsc20259	PD 0:00	1 (Dependency)	
24870	vaughan job_mult vsc20259	PD 0:00	1 (Dependency)	
24868	vaughan job_lead vsc20259	R 0:25	1 r1c01cn1	
Some time later:				
JOBID	ARTITION NAME USEF	R ST TIME	NODES NODELIST(REASON)	
24869	vaughan job_mult vsc20259	R 0:01	1 r1c01cn1	
24870	vaughan job_mult vsc20259	R 0:01	1 r1c01cn1	
When finished: Out	put of ls:			
job_depend.slurm	job_launch.sh mult-10 ou	Itputfile	slurm-24869.out	
job_first.slurm	job.slurm mult-5 s]	urm-24868.out	slurm-24870.out	
cat outputfile	10			
cat mult-5/output	file 50			
cat mult-10/outpu	tfile 100			VLAAMS SUPERCOMPUTER



Interactive jobs Method 1: srun for a non-X11 job

- Use the regular resource request options on the command line of srun and end with --pty bash
- > Example: An interactive session to run a shared memory application

```
login$ srun -n 1 -c 16 -t 1:00:00 --pty bash
rXcYYcnZ$ module --force purge
rXcYYcnZ$ ml calcua/2020a vsc-tutorial
rXcYYcnZ$ omp_hello
...
rXcYYcnZ$ exit
```

> Example: Starting an MPI program in an interactive session

```
login$ srun -n 64 -c 1 -t 1:00:00 --pty bash
rXcYYcnZ$ module --force purge
rXcYYcnZ$ ml calcua/2020a vsc-tutorial
rXcYYcnZ$ srun mpi_hello
...
rXcYYcnZ$ exit
```

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Globus

- > Service to transfer large amounts of data between computers
 - It is possible to initiate a direct transfer between two remote computers from your laptop (no software needed on your laptop except for a recent web browser)
 - o It is also possible to initiate a transfer to your laptop
 - Globus software needed on your laptop
 - After disconnecting, the transfer will be resumed automatically
- > Via web site: globus.org
 - o It is possible to sign in with your UAntwerp account
 - You can also create a Globus account and link that to your UAntwerp account
- > You do need a UAntwerp account to access data on our servers
 - o Data sharing features not enabled in our license
- > Collection to look for in the Globus web app: VSC UAntwerpen Tier2
 - From there access to /data (vsc2* accounts only) and /scratch (all users)
 - Note: VSC is also Vienna Scientific Cluster







